

# **The basics of homology**

Aaron Fenyes (IHÉS)

Young Data Scientist Seminar

Harvard, November 2020

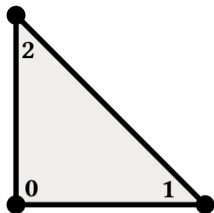
# Building geometric spaces



standard 0-simplex



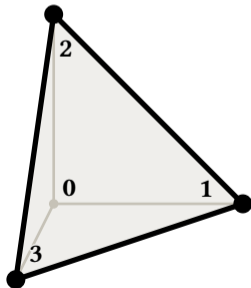
standard 1-simplex



standard 2-simplex

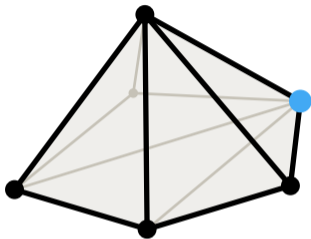
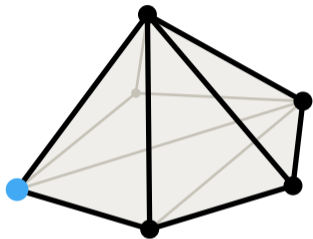
A  $\Delta$ -*complex* is a space built from simplices, which attach to each other by sharing faces.

(In a *simplicial complex*, no two simplices have the same set of vertices.)



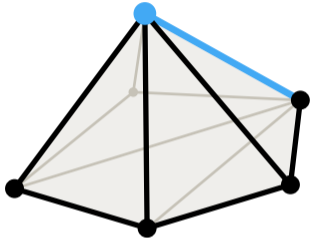
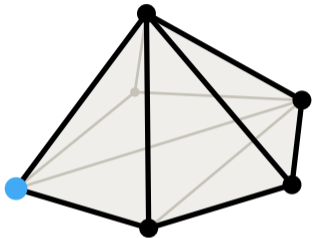
standard 3-simplex

# Investigating deformations of points



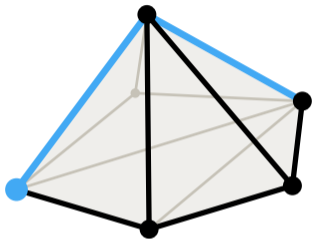
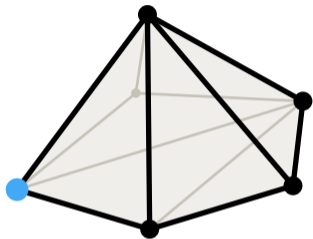
Can these points be deformed into each other?

# Investigating deformations of points



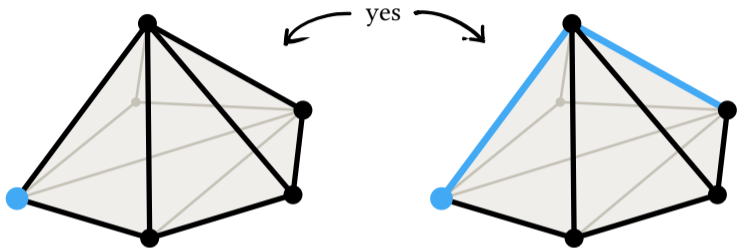
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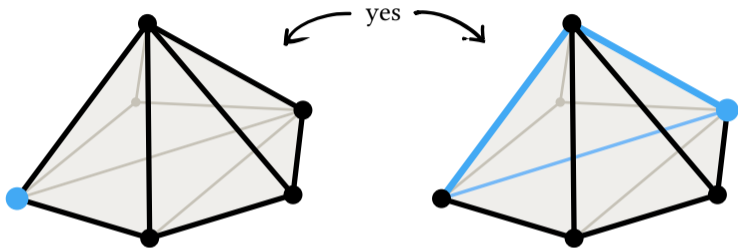
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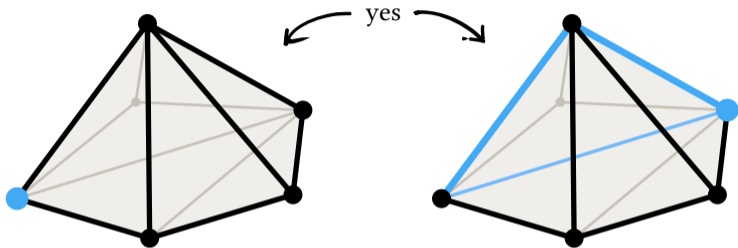
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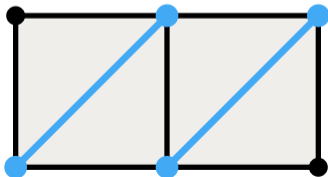
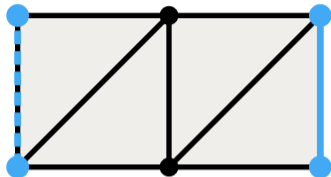
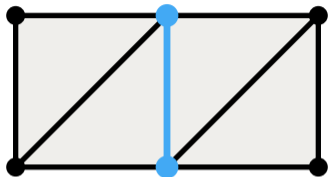
Can these points be deformed into each other?

It's easy to decide.



# Investigating deformations of loops

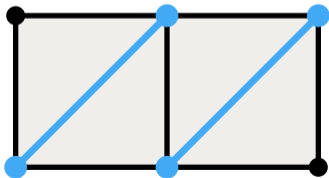
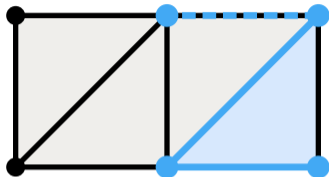
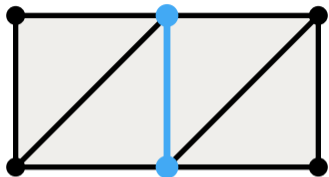
(Identify opposite edges)



Can these loops be deformed into each other?

# Investigating deformations of loops

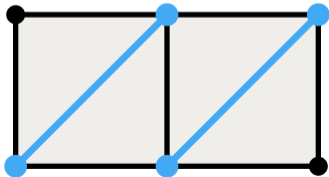
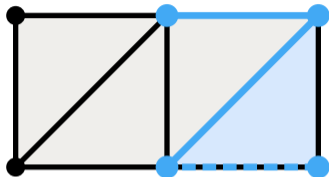
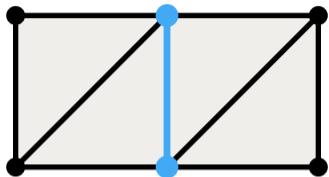
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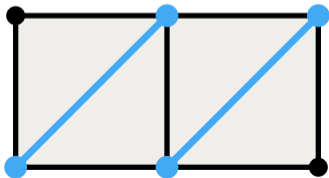
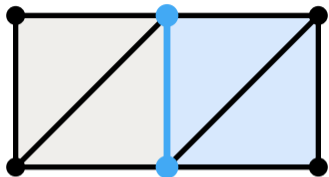
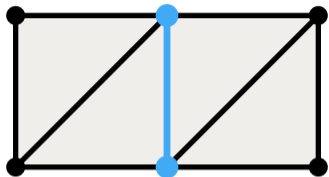
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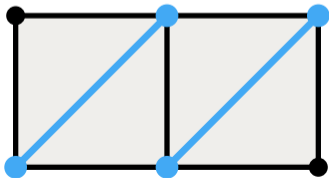
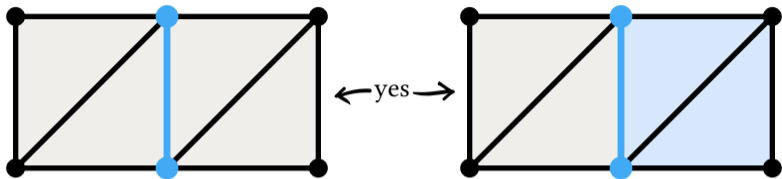
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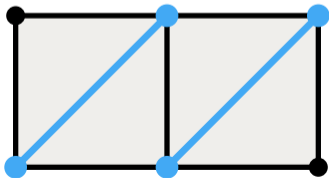
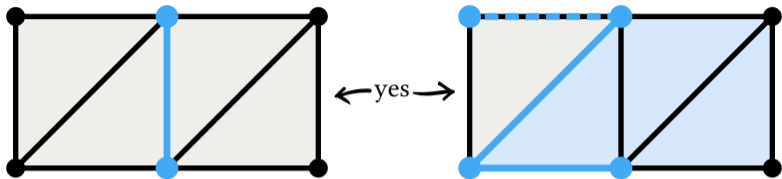
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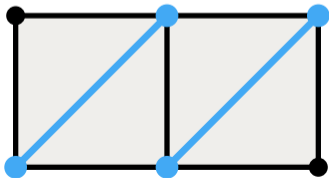
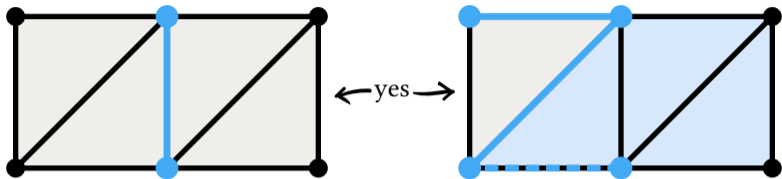
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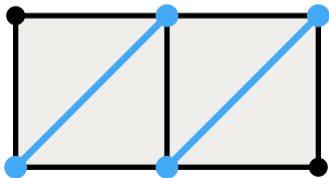
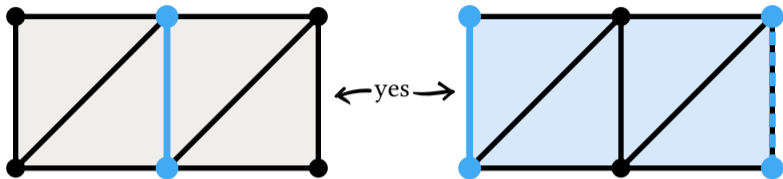
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(Identify opposite edges)

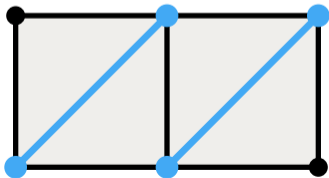
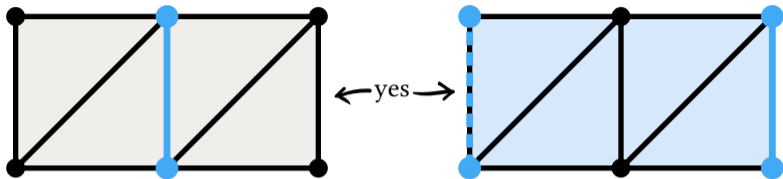


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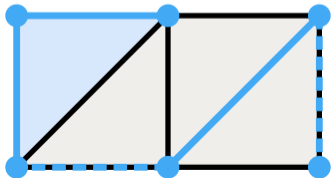
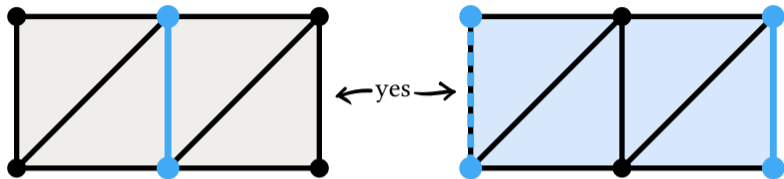
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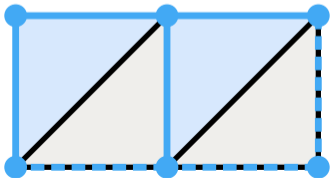
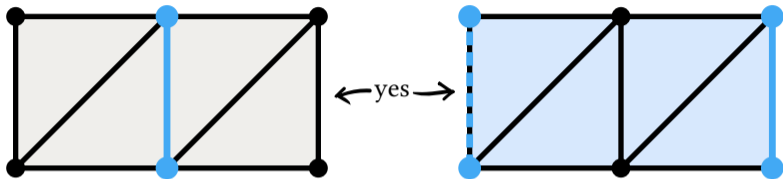
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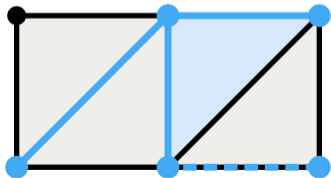
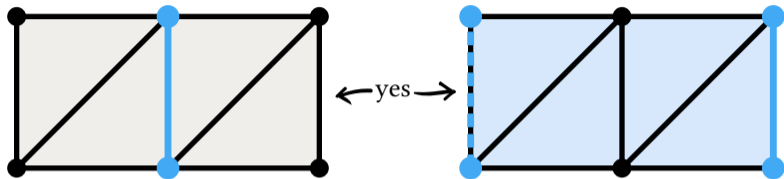
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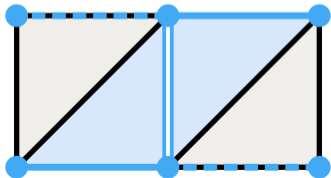
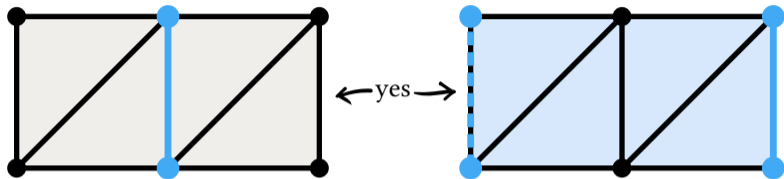
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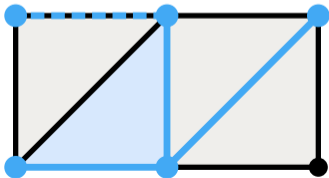
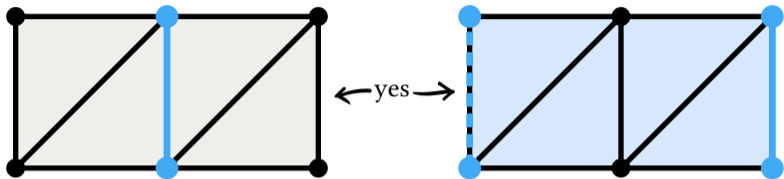
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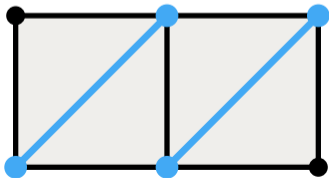
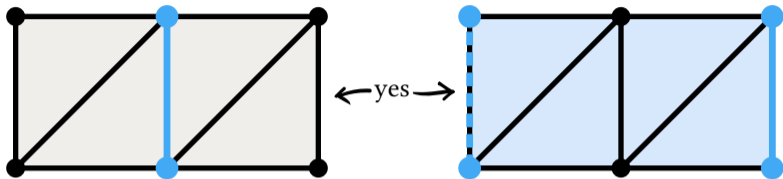
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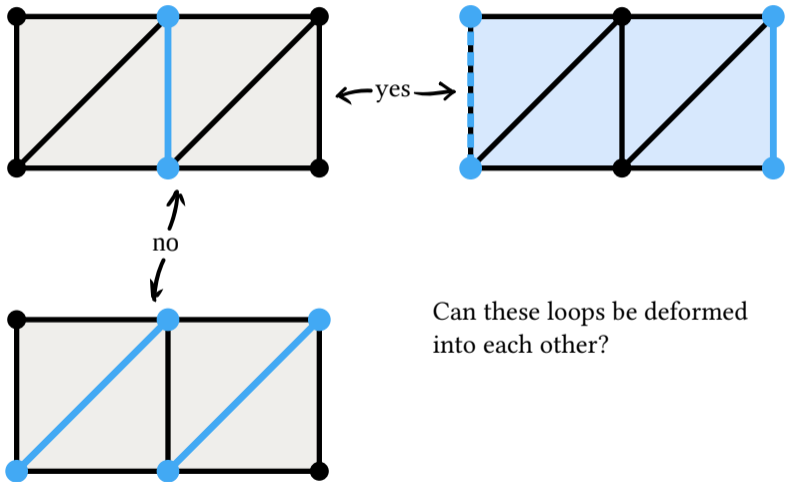
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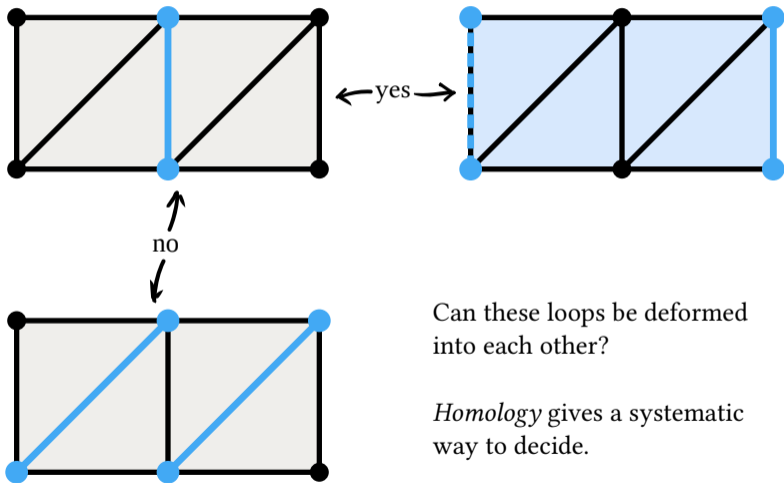
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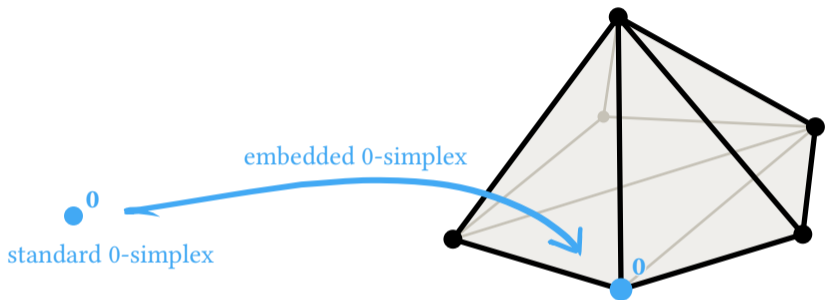
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Can these loops be deformed into each other?

*Homology* gives a systematic way to decide.

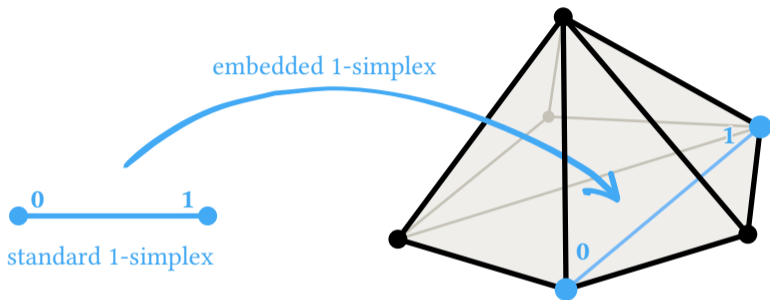
# Turning geometry into algebra



An *embedded simplex* is a map that sends the standard  $n$ -simplex to one of the  $n$ -simplices of a  $\Delta$ -complex.

Ordering the vertices of the standard  $n$ -simplex makes it easy to see where the map sends each vertex.

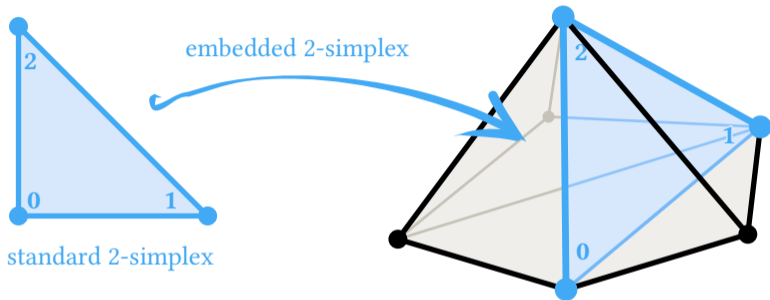
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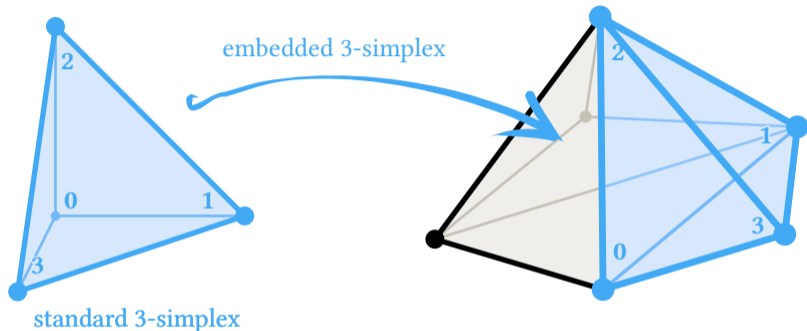
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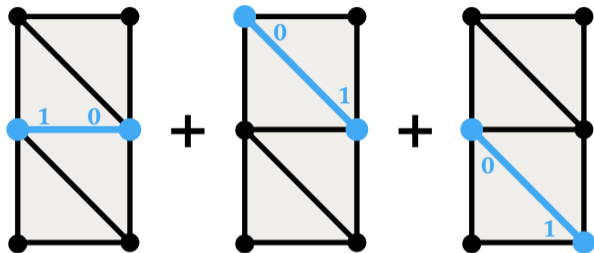


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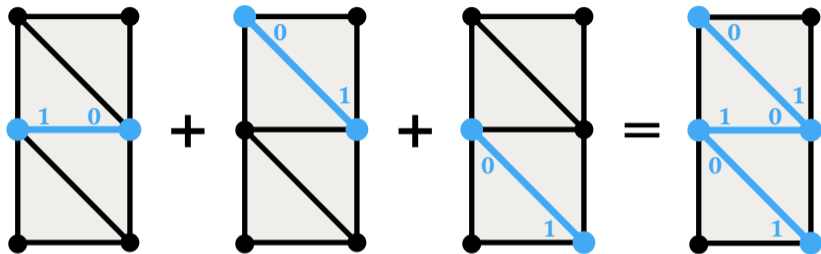
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An  $n$ -chain is a “formal sum” of embedded  $n$ -simplices.

# Turning geometry into algebra

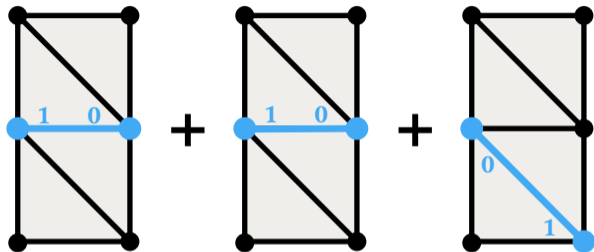
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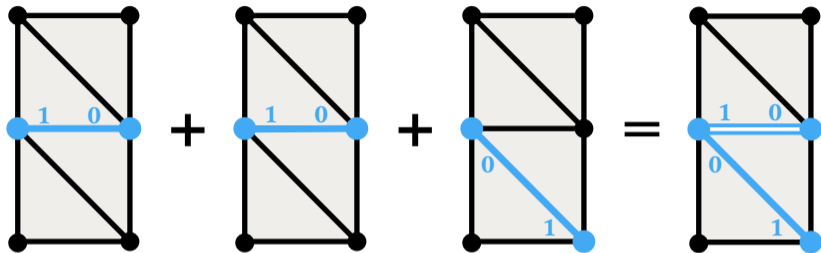
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A simplex can appear more than once in the sum.



# Turning geometry into algebra

(Identify opposite edges)

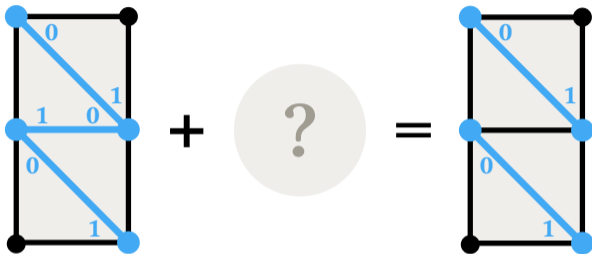


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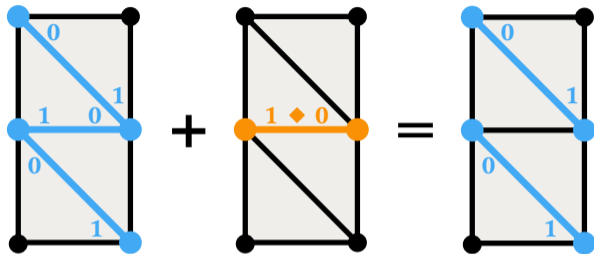
An  $n$ -chain is a “formal sum” of embedded  $n$ -simplices.

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For algebraic convenience, we allow negative simplices.

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(Identify opposite edges)

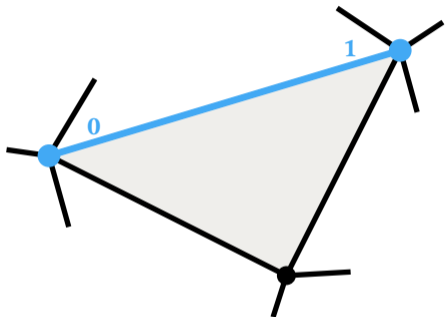


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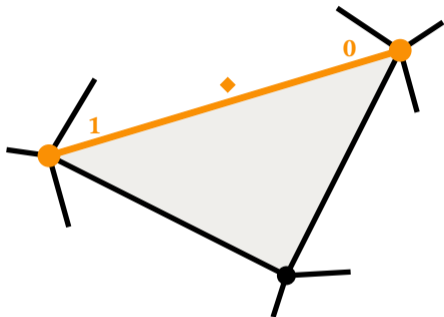
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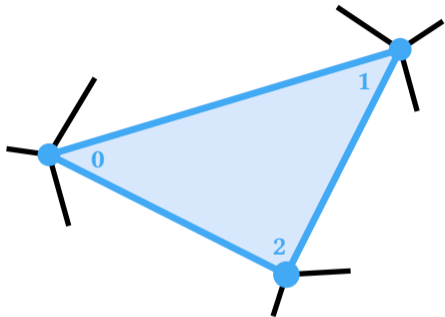
Sign rule: swapping two vertices of an embedded simplex is equivalent to reversing its sign.

# Turning geometry into algebra



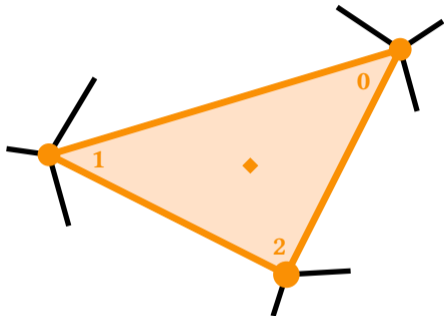
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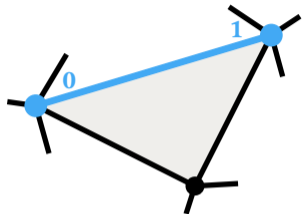
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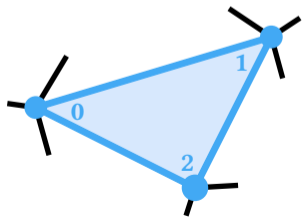
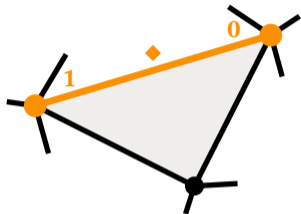


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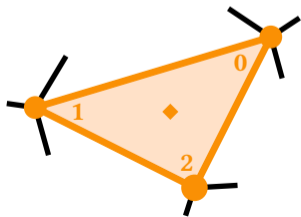
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$\sim$   
sign rule

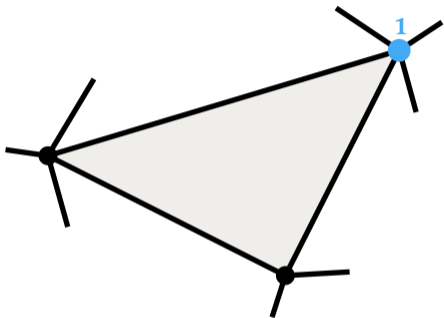


$\sim$   
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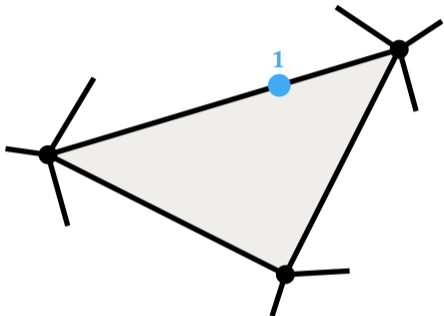


## Describing deformations as substitution rules



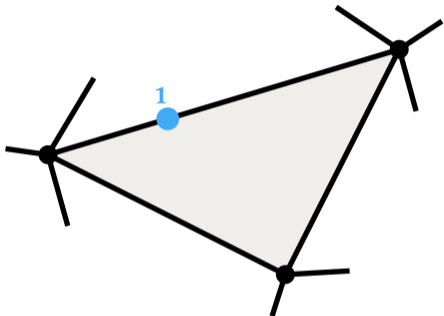
You can deform a 0-simplex by pushing it across a 1-simplex.

## **Describing deformations as substitution rules**



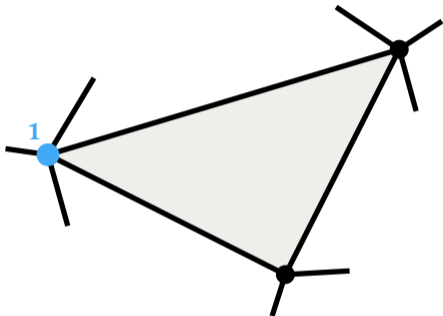
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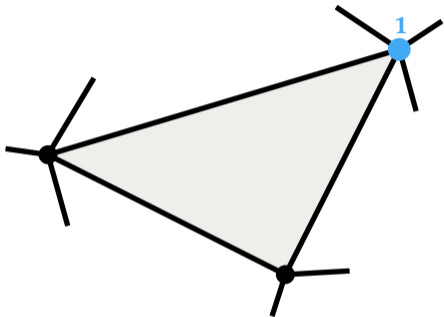
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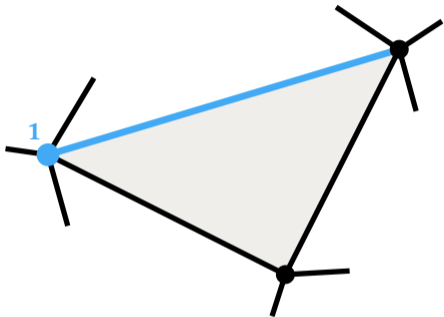
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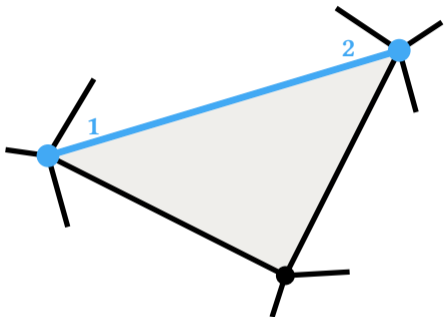
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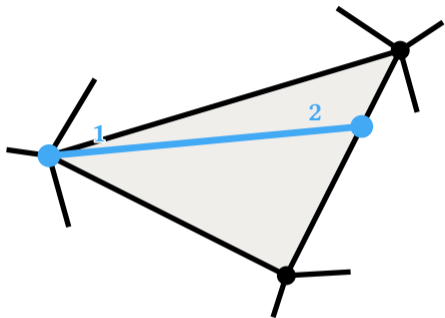
You can deform a 0-simplex by pushing it across a 1-simplex.

## Describing deformations as substitution rules



You can deform a 1-simplex by pushing it across a 2-simplex.

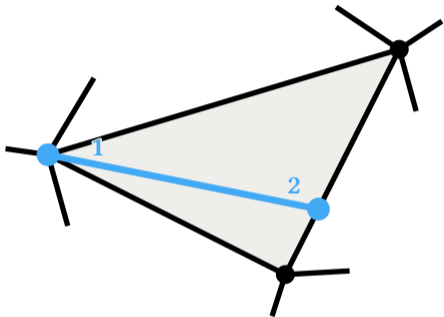
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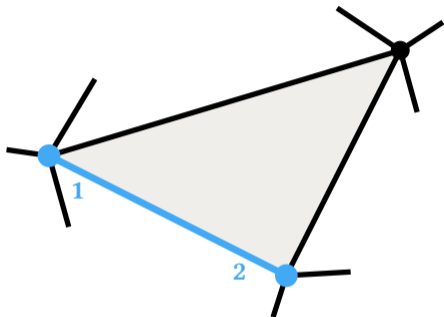


## Describing deformations as substitution rules



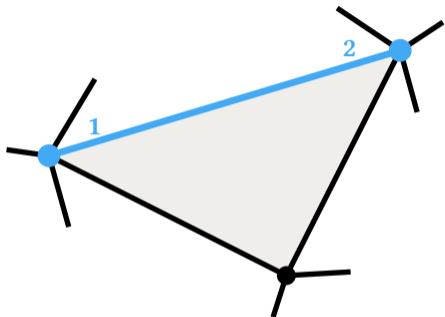
You can deform a 1-simplex by pushing it across a 2-simplex.

## Describing deformations as substitution rules



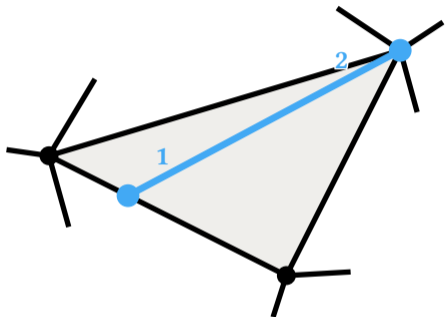
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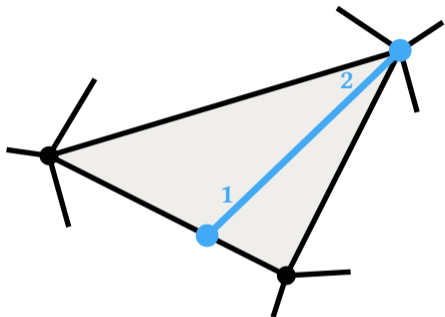
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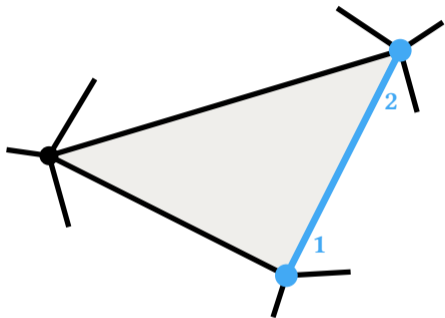
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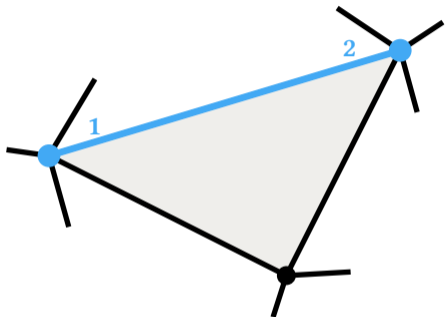
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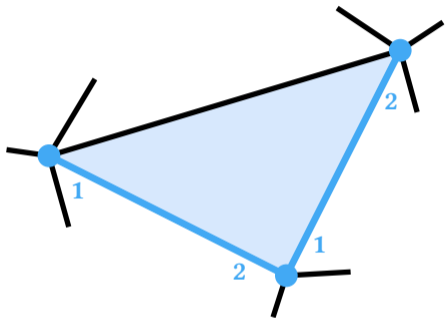
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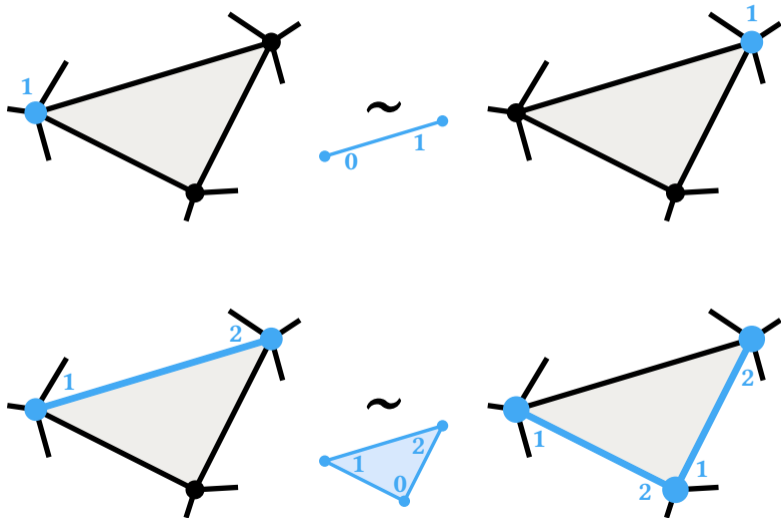
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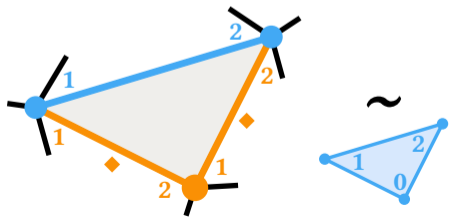
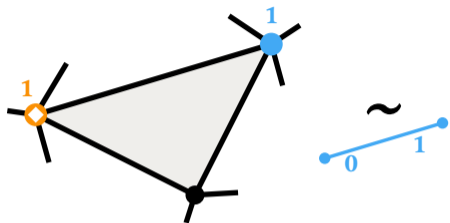
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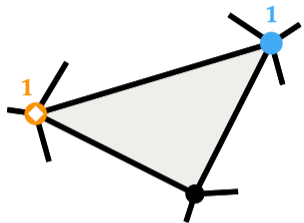
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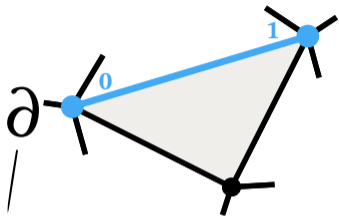
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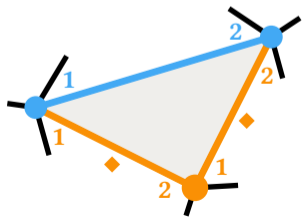
# Keeping track of deformation substitutions



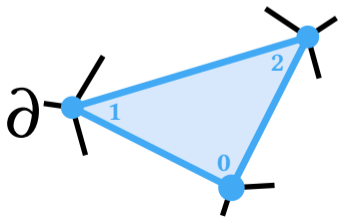
=



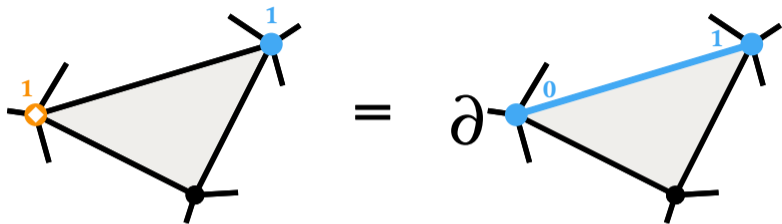
*boundary  
operator*



=

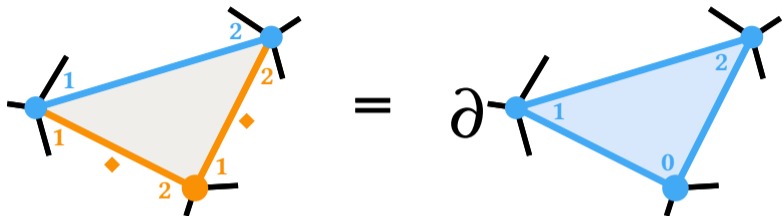


## Keeping track of deformation substitutions



The *boundary operator* sends each embedded  $(n+1)$ -simplex to the  $n$ -chain that describes deformation across the simplex.

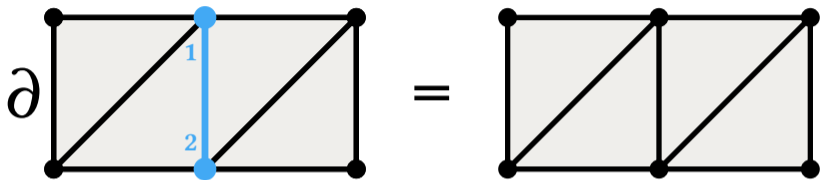
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## Deformation problems as algebra problems

(Identify opposite edges)

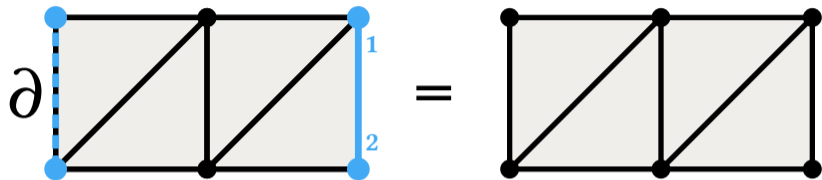


The boundary operator, unexpectedly, characterizes closed loops, and “closed-up shapes” in higher dimensions.

An  $n$ -chain  $C$  is called an  $n$ -cycle if  $\partial C = 0$ .

## Deformation problems as algebra problems

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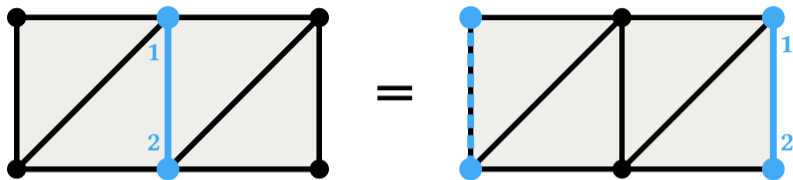


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For  $n$ -cycles  $A, B$ , these are equivalent:

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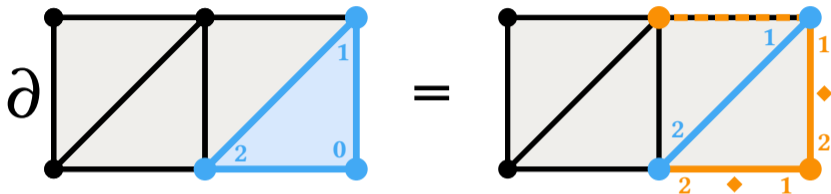
$\partial$

?



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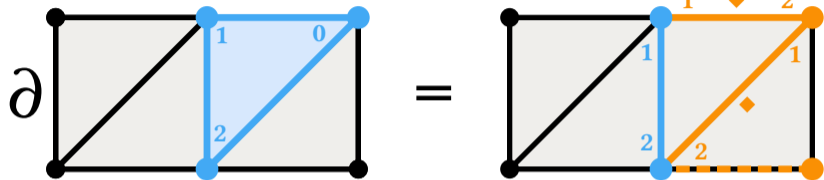


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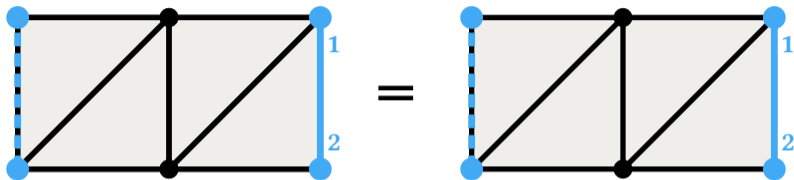


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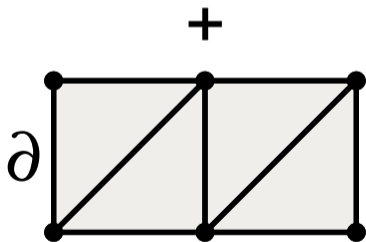
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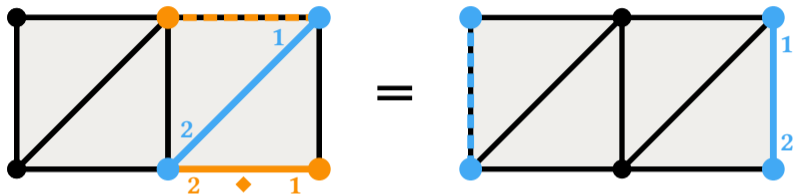
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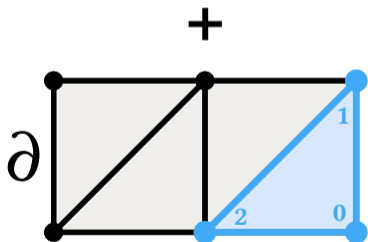
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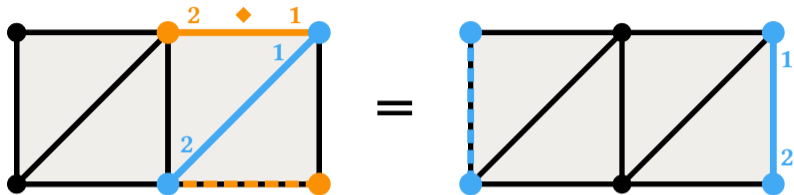
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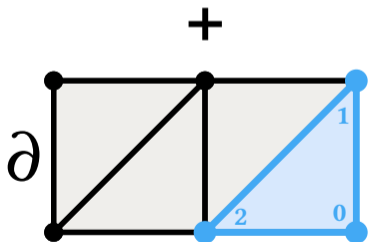
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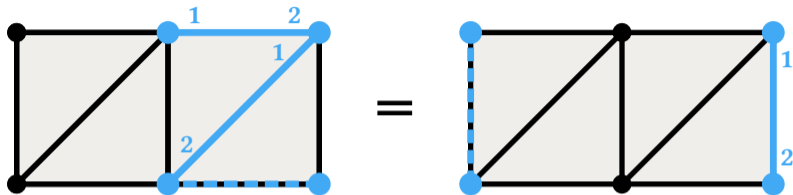
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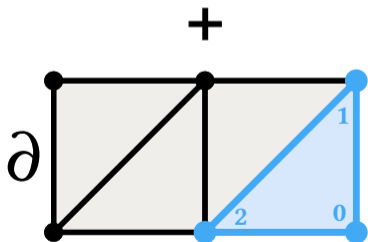
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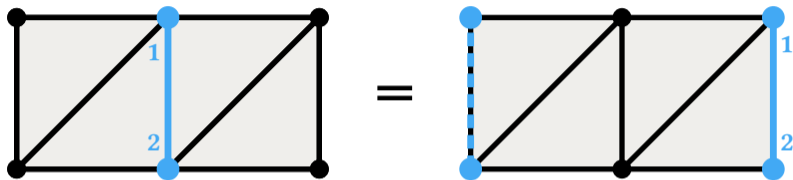
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