

c) If  $D_1 = D_2$ ,  $S = 1$ :

$$(3) \quad X_A = \int d\mu(g) D(g) A D^{-1}(g) = \alpha(A) I.$$

If one takes  $A$  such that  $\text{tr } A$  is well defined and  $\neq 0$  (and this is possible e.g. when  $A$  has finite rank), one obtains:

$$\text{tr } X_A = \int d\mu(g) \text{tr } A = \alpha(A) d_D,$$

where  $d_D$  is the dimension of  $D$ .

Now if (1) would be 0, we would have had  $X_A = 0$  hence  $\text{tr } X_A = \text{tr } A = 0$ ; which is contradictory. Hence  $\alpha(A) \neq 0$  and  $d_D$  is the finite number  $d/\alpha$ .

**THEOREM 2.** - Any irreducible representation of a compact group has finite dimension.

Application to Abelian groups: Take

$$A = D(g_0), \quad g_0 \in G; \quad \rightarrow X = D(g_0) = \alpha I;$$

since the representation is irreducible, it must then have dimension 1.

*Orthogonalization relations.* - Since the  $D(g)$  have finite dimension, they can be represented by matrices.

Let us choose

$$A = [c_{jk}] = j - \begin{pmatrix} 0 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 1 \end{pmatrix}$$

Then

$$(X_A)_{rs} = \int d\mu(g) D_{rr}^{(g)}(g) D_{kk}^{(g)}(g^{-1}) = \delta_{rs} \quad \begin{matrix} \delta_{jk} & \frac{1}{d_D} & \delta_{ll} \\ \downarrow & & \downarrow \\ 0 & \text{if } D^r \neq D^s & D^s \end{matrix} \quad \begin{matrix} \alpha(A) = \text{tr } A/d \\ (I)_{ll} \\ \text{for } r = s \end{matrix}$$

or, since  $D(g^{-1}) = D^{-1}(g) = D^*(g) = D_r(g)$ :

$$(4) \quad \int d\mu(g) D_{rr}^{(g)}(g) D_{ll}^{(g)}(g) = \frac{1}{d_D} \delta_{rs} \delta_{jk} \delta_{ll}.$$

Thus:

**THEOREM 3.** - The functions  $D_{ij}^{(g)}(g)$  form an orthogonal set of functions in  $L^2(G)$  (the set of square integrable functions on  $G$ ).

One can prove that  $D_{ij}^{(g)}(g)$  form a complete basis of this Hilbert space (Peter-Weyl theorem).

One can also prove that  $L^{-2}(g)$  is separable; therefore there is at most a denumerable set of inequivalent irreducible representations.

*Reality condition for irreducible representation.* — Let us now define

$$Y = \int d\mu(g) D(g) A D^{-1}(g).$$

If  $D$  is a unitary representation,  $\bar{D} = D^{-1x}$  is also a representation.

By the same technique we prove  $DY = Y\bar{D}$ :

— If  $D \not\sim \bar{D}$ ,  $Y = 0$ .

— If  $D \sim \bar{D}$ ,  $\exists S \rightarrow \bar{D} = S^{-1} D S = D^{-1x}$

$$Y = \int d\mu(g) D(g) A D^x(g) = \alpha(A) S.$$

Now,

$$D = \bar{S}^{-1} \bar{D} \bar{S},$$

hence  $\bar{S} \bar{S} = \lambda I$  (Schur's lemma),

$$D^{*-1} = D = S^x D^{-1x} S^{-1x},$$

hence  $S^{-1x} S = \lambda' I$  (Schur's lemma),

*i.e.*  $S^x = CS \rightarrow C^2 = 1 \rightarrow S^x = \pm S$  by convenient choice of a factor. The  $S$  can be made unitary, hence  $\bar{S} \bar{S} = C$ .

— If  $D \sim$  to a real representation  $\bar{S}$  is a multiple of the unit matrix and therefore  $S^x = +S$ , *i.e.*  $C = 1$  (use the fact that  $C$  does not depend on an equivalence). It is easy to prove that this necessary condition is sufficient.

Let  $\omega \neq$  all proper values of  $\bar{S}$  and  $|\omega| = 1$ ; then  $D' = (\bar{S} - \omega) D (\bar{S} - \omega)^{-1} = \bar{D}$

— If  $D \not\sim$  to a real representation  $S^x = -S$ .

Thus for any  $A$

$$(5) \quad \int d\mu(g) D(g) A^x D^x(g) = \pm \int d\mu(g) D(g) A D^x(g)$$

*Characters.* — The trace of a representation  $D(g)$  is called its character  $\chi^{(v)}(g) = \text{tr } D^{(v)}(g)$ . Since  $\text{tr } D = \text{tr } SDS^{-1}$ , the characters are defined on representations up to an equivalence. If two elements  $g, h$  are conjugate ( $\exists a \rightarrow g = aha^{-1}$ ), then  $\chi^{(v)}(g) = \chi^{(v)}(h)$ ; the character is the same for all members of a conjugate class in the group. One has from (4) with  $i = j, k = l$

$$(6) \quad \int d\mu(g) \chi^{(v)}(g) \bar{\chi}^{(v)}(g) = \delta_{rs}$$

Furthermore, from (5) with  $A = [e_{jk}]$  one gets:

$$Y_i = \int d\mu(g) D_{ii}(g) D_{kk}(g) = \pm \int d\mu(g) D_{ik}(g) D_{ki}(g).$$

Taking the trace: ( $j = l, i = k, \Sigma_{r,1}$ ) one has:

$$\int d\mu(g) \chi(g^2) = \pm \int d\mu(g) \chi^2(g) = \int d\mu(g) \chi(g) \overline{\chi}(g) = 1$$

(since  $\overline{D} \sim D$  if  $Y \neq 0$ ).

**THEOREM 4.**

$$\begin{aligned} D \sim \overline{D} \quad \text{and} \quad D \sim \text{real rep.} &\Leftrightarrow \int d\mu(g) \chi(g^2) = +1 \\ \text{and} \quad D \not\sim \text{real rep.} &\Leftrightarrow \int d\mu(g) \chi(g^2) = -1 \\ D \not\sim \overline{D} &\Leftrightarrow \int d\mu(g) \chi(g^2) = 0 \end{aligned}$$

*Peter-Weyl Theorem.* - The original proof makes use of the spectral theory of Hermitian operators. We give a simpler proof due to STONE. It is valid only for groups with faithful representations.

**THEOREM.** - The functions  $D_{ij}^{(r)}(g)$  of  $g \in G$  form a complete basis in the space  $L^2(G)$ , i.e. if  $\varphi(g)$  is orthogonal to  $D_{ij}^{(r)}(g)$  for all  $r, i, j$ , it is the zero function. This basis is uniformly complete, i.e. all  $\varepsilon > 0$ .

$\exists$  a finite linear combination  $f_\varepsilon$  s.t.  $|f_\varepsilon(g) - \varphi(g)| < \varepsilon$  for any  $g$ . In what follows  $D_{ij}^{(r)}$  is assumed to be real; for, if it is not, the representation formed by the direct sum  $D^{(r)} \oplus D^{(r)}$  is equivalent to a real representation:

$$S \begin{pmatrix} D^{(r)} & \\ & D^{(r)} \end{pmatrix} S^{-1} = \frac{1}{2} \begin{pmatrix} D + \overline{D} & i(D - \overline{D}) \\ -i(D - \overline{D}) & D + \overline{D} \end{pmatrix}$$

where

$$S = \frac{1}{\sqrt{2}} \begin{pmatrix} i & i \\ -1 & 1 \end{pmatrix}$$

Let  $D$  be a real faithful representation of  $G$ .

Consider the Kronecker products

$$\otimes^n D$$

for all  $n$

(note that the Kronecker product of two representations is itself a representation since  $(A \otimes B)(A' \otimes B') = AA' \otimes BB'$ ).

We shall prove that the representation  $(\otimes^n D)_{i_1, j_1, \dots, i_n, j_n}$  form a complete set, so the same holds for the irreducible representations.

Suppose there exists  $\varphi(g)$  orthogonal to all  $(\otimes^n D)_{i_1, j_1, \dots, i_n, j_n}$  and different from zero in some neighbourhood of  $g_0$ .

Construct

$$f(g, N) = A(N) \exp \left[ -N \sum_{ij} \{D_{ij}(g) - D_{ij}(g_0)\}^2 \right],$$

where  $A(N)$  is chosen so that

$$\int d\mu(g) f(g, N) = 1.$$

It is well known that a function of the form of  $f(g, N)$  can be expanded as a power series with an infinite radius of convergence. The terms in the series are evidently linear combinations of the  $(\otimes^n D)_{ij}$ .

$$\lim_{N \rightarrow \infty} \int d\mu(g) f(g, N) = 1$$

but  $f(g, \infty) = 0$  for  $g \neq g_0$  so that  $f(g, \infty) = \delta(g - g_0)$ .

If  $\varphi(g)$  were orthogonal to all  $(\otimes^n D)_{ij}$  then one would have

$$\lim_{N \rightarrow \infty} \int d\mu(g) \bar{f}(g, N) \varphi(g) = 0,$$

but

$$\lim_{N \rightarrow \infty} \int d\mu(g) \bar{f}(g, N) \varphi(g) = \varphi(g_0),$$

which by hypothesis is different from zero. Thus  $(\otimes^n D)_{ij}$  form a complete set and can be decomposed into a direct sum of irreducible representations which is complete.

*This proof shows also that:*

- 1) The set of irreducible representations is at most denumerable.
- 2) Any faithful representation generates, by  $\otimes$ , all the irreducible representations.

*Example.* - The two-dimensional rotation group: if  $\varphi$  is the angle of rotation  $D^{(n)}(\varphi) = \exp[in\varphi]$  ( $n$  integer)

$$\int_0^{2\pi} \exp[in\varphi] \exp[-im\varphi] \frac{d\varphi}{2\pi} = \delta_{nm}.$$

We have therefore proved that for the Hilbert space of square integrable functions defined on the interval  $(0, 2\pi)$ , the functions  $\exp[in\varphi]$  form an orthonormal complete set.

*Finite groups.* - Let  $N_g$  be the number of elements of the group. The complex-valued functions defined on the group form a  $N_g$  dimensional linear space (Exercise in GARDING's note). We have show that the  $\sum_r a_{D^{(r)}}^2 \mathcal{Q}_G^{(r)}$ -functions are orthonormal. Since they form a complete set we can conclude

$$\sum_r d_{D^{(r)}}^2 = N_g.$$

*The decomposition of a given representation of a compact group into a direct sum of irreducible representations.*

From Theorem 1, we can make it unitary.

First case: *The representation is finite dimensional.*

Then the accident mentioned at the bottom of page 7 will not occur. The representation is a direct sum of irreducible representations.

Let

$$(7) \quad U(g) = \bigoplus_r n_r D^{(r)}(g),$$

where  $n_r$  is number of times the irreducible representation  $D^{(r)}(g)$  occurs in  $U(g)$ . Then

$$\chi(U(g)) = \sum_r n_r \chi^{(r)}(g)$$

and from (6)

$$n_r = \int d\mu(g) \bar{\chi}^{(r)}(g) \chi(U(g)).$$

If the representation is infinite one has to be more careful.

Let

$$E_{ii}^{(r)} = d_{D^{(r)}} \int d\mu(g) D_{ii}^{(r)}(g) U(g);$$

one can prove

$$E_{ii}^{(r)*} = E_{ii}^{(r)}.$$

Let

$$E^{(r)} = \sum_i E_{ii}^{(r)} = d_{D^{(r)}} \int d\mu(g) \bar{\chi}^{(r)}(g) U(g);$$

calculation yields that  $E^{(r)}$  are the projection operators in Hilbert space onto the subspace  $\mathcal{H}^{(r)}$  on which act the  $\bigoplus$  of representations equivalent to  $D^{(r)}$  occurring in the direct sum of  $U$ .

The character  $\chi$  function only of the conjugation class  $C$  and not of each group element. Let  $N_c$  be the number of such classes.

The characters  $\chi^{(\alpha)} \in C$  span a vector space of at most  $N_G$  dimensions. Since they are linearly independent (equation (6)) the number  $N_D$  of irreducible inequivalent representations is  $\leq N_G$ .

**THEOREM.** - For finite groups  $N_D = N_G$ .

Consider the  $N_G$  dimensional linear space of formal linear combinations of group elements. The group multiplication generates naturally a  $N_G$  dimensional linear representation on this space, the so called regular representation  $D_G$ . It can be shown that  $D_G$  contains all the irreducible representations, each one  $d_\rho(x)$  times. We shall not prove it here.

#### 4. - Structure of the Lorentz group.

*Notation.* - An event in space time is specified by the four numbers  $(ct, \mathbf{r})$ . We denote 3-dimensional vectors with an arrow above  $\mathbf{r} = (x^i)$ ;  $i = 1, 2, 3$ . We denote 4-dimensional vectors with a bar below:  $\mathbf{x} = (x^\mu)$ ;  $\mu = 0, 1, 2, 3$ . ( $x^0 = ct$ ).

The separation between two events,  $\mathbf{x}, \mathbf{y}$  is given by:

$$(x - y)^2 = (\mathbf{x} - \mathbf{y}) \cdot (\mathbf{x} - \mathbf{y}) = (x^0 - y^0)^2 - \sum_{i=1}^3 (x^i - y^i)^2.$$

We define the metric tensor:  $G$

$$\mathbf{x} \cdot \mathbf{y} = \mathbf{x} G \mathbf{y} = x^0 y^0 - \sum_{i=1}^3 (x^i y^i) = x^\mu g_{\mu\nu} y^\nu; \quad G = (g_{\mu\nu}) = \begin{pmatrix} 1 & & & 0 \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix}$$

We define  $g^{\mu\nu}$  as the elements of  $G^{-1} = G$

$$g^{\mu\sigma} g_{\sigma\nu} = g^\mu_\nu = \delta^\mu_\nu \quad (\text{The summation convention is understood}).$$

We define the covariant components of a vector

$$x_\mu = g_{\mu\nu} x^\nu.$$

*Definition of Lorentz group.* - The group  $\mathcal{L}$  of all linear transformations  $\mathbf{x} \rightarrow \mathbf{x}'$  such that  $(\mathbf{x}' - \mathbf{y}')^2 = (\mathbf{x} - \mathbf{y})^2$ . Unless otherwise specified, we shall limit ourselves to the real transformations.

So, we write:

$$x'^\mu = A^\mu_\nu x^\nu + a^\mu,$$

$a = \{a^\mu\}$  is called the translation  $\mathbf{r}T$ ;

$A = \{A^\mu_\nu\}$  is called a homogeneous transformation:  $\mathbf{r}L$ .

The most general Lorentz transformation is called inhomogeneous.

The inhomogeneous group will be noted by  $\mathcal{L}$ .

Given a homogeneous transformation  $A$  and a translation  $a$ , one denotes the operation  $\mathbf{x} \rightarrow \mathbf{x}' = \{x'^{\mu} = A^{\mu}_{\nu} x^{\nu} + a^{\mu}\}$  by:  $\{a, A\}$ , being understood that  $A$  is performed first.

Multiplication law:

$$\{a, A\} \{b, M\} = \{a + Ab, AM\}.$$

Neutral element (unity):  $\{0, 1\}$ .

Inverse:

$$\{a, A\}^{-1} = \{-A^{-1}a, A^{-1}\}$$

$$\{a, A\} = \{a, 1\} \{0, A\} \quad \text{i.e. } \mathcal{L} = T \cdot L.$$

Both  $T$  and  $L$  are subgroups of  $\mathcal{L}$ .

*Invariant subgroups.* —  $H$  is an invariant subgroup of  $\mathcal{L}$  if for all  $\{a, A\} \in \mathcal{L}$ ,  $\{b, M\} \in H$

$$\{a, A\} \{b, M\} \{a, A\}^{-1} = \{a + Ab - AM A^{-1}a, AM A^{-1}\} \in H.$$

One can easily see that  $T$  is an invariant subgroup.

The cosets of  $\mathcal{L}$  modulo  $T$  are:

$$\{a, A\} \{b, 1\} = \{a + Ab, A\}.$$

The quotient group  $\mathcal{L}/T$  is isomorphic with  $L$ .

$\mathcal{L} = T \cdot L$  but  $\mathcal{L} \neq T \times L$  because, whereas  $T$  is an invariant subgroup,  $L$  is not.  $\mathcal{L}$  is sometimes called the *semi* direct product of  $T$  and  $L$ . The multiplication law is easily remembered by writing in matrix form:

$$\{a, A\} \rightarrow \begin{vmatrix} 1 & 0 \\ a & A \end{vmatrix}.$$

(Another illustration of a reducible representation which is not completely reducible).

— Translation group.  $T$ .

*The homogeneous group. L. Its four pieces.* — Since  $\mathcal{L}$  leaves invariant  $(\mathbf{x} - \mathbf{y})^2$ , it leaves invariant  $\mathbf{x}^2$  (put  $\mathbf{y} = 0$ ),  $\mathbf{y}^2$  (put  $\mathbf{x} = 0$ ), and therefore  $\mathbf{x} \cdot \mathbf{y}$ :

$$\mathbf{x} \cdot \mathbf{y} = \Lambda \mathbf{x} \cdot \Lambda \mathbf{y}, \quad \text{i.e.} \quad x^{\alpha} g_{\alpha\beta} y^{\beta} = \Lambda^{\mu}_{\alpha} x^{\alpha} \Lambda^{\nu}_{\beta} y^{\beta} g_{\mu\nu};$$

as this must be true for all  $\mathbf{x}$ ,  $\mathbf{y}$ , one has:

$$\Lambda^\mu_\alpha \Lambda^\nu_\sigma g_{\mu\nu} = g_{\alpha\sigma} \quad \text{or} \quad G = \Lambda^T G \Lambda.$$

This is necessary and sufficient.

The invariance of  $\mathbf{x} \cdot \mathbf{x} = \mathbf{x}^2$  under  $\Lambda \in L$  allows us to distinguish between

time-like vectors  $\bullet \mathbf{x}^2 > 0$ ,

light-like vectors  $\mathbf{x}^2 = 0$ ,

space-like vectors  $\mathbf{x}^2 < 0$ .

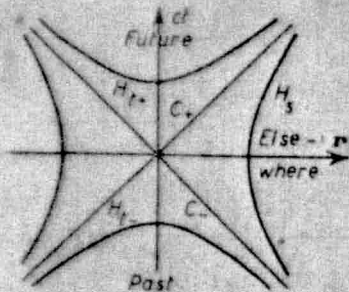


Fig. 3.

In the affine space (set of points  $\theta + \mathbf{x}$ ), the sets of points such that  $\mathbf{x}^2 = c > 0$  is the two piece hyperboloids  $\mathcal{H}_{t+}$  ( $x^0 > 0$ ) and  $\mathcal{H}_{t-}$  ( $x^0 < 0$ ).

$\mathbf{x}^2 = 0$  is the light cone  $C$ ,  $C_+$  ( $x^0 > 0$ ) and  $C_-$  ( $x^0 < 0$ );

$\mathbf{x}^2 = c < 0$  is the one piece hyperboloid  $\mathcal{H}_s$ .

Note if  $\mathbf{x}'^2 = \mathbf{x}^2 = c < 0$  one can go continuously from

$$\mathbf{x} \rightarrow \mathbf{x}'.$$

If  $c > 0$ , it is possible only if  $x'^0 x^0 > 0$ .

*Connection of  $L$ .* - One has  $\det G = \det \Lambda^T G \Lambda$ , thus  $\det \Lambda^T \Lambda = (\det \Lambda)^2 = 1$  so that  $\det \Lambda = \pm 1$ .

One cannot go by a homomorphism from unity ( $\det 1 = 1$ ) to a  $\Lambda$  for which  $\det \Lambda = -1$ ;  $L$  is therefore composed of two disconnected parts:

$L_+ = \{\Lambda, \det \Lambda = +1\}$  which is the invariant subgroup of proper Lorentz transformations,

$L_- = \{\Lambda, \det \Lambda = -1\}$  which is the set of improper Lorentz transformations (and is *not* a subgroup).

$L/L_+$  consists of two elements.

Now consider real Lorentz transformations: (the complex homogeneous group is denoted by  $CL$ ).

One has:

$$g_{00} = \Lambda^0_\alpha \Lambda^0_\sigma g_{\alpha\sigma} = 1 = (\Lambda^0_0)^2 - \sum_i (\Lambda^i_0)^2,$$

thus

$$(\Lambda^0_0)^2 = 1 + \sum_i (\Lambda^i_0)^2 \geq 1,$$



Thus:

$$A_0^0 > 1 \quad \{1, A_0^0 > 1\} = L^+ : \text{ orthochronous group} \\ \text{(invariant subgroup),}$$

or

$$A_0^0 < -1 \quad \{1, A_0^0 < -1\} = L^- : \text{ antichronous transformations} \\ \text{(not a subgroup).}$$

The justification of the terminology is the following:

$A_0^0 > 1 \Rightarrow$  the sign of the time component of a true like vector is not changed:

$$x^{0'} = A_{0\mu}^0 x^\mu = A_0^0 x^0 + A_i^0 x^i,$$

$$\left(\sum_i A_i^0 x^i\right)^2 \leq \left(\sum_i A_i^0\right)^2 \left(\sum_i x^i\right)^2 = [(A_0^{02})^2 - 1] \sum_i (x^i)^2 < (A_0^0)^2 (x^0)^2, *$$

(\* for a time like vector:  $\sum (x_i)^2 < (x^0)^2$ .)

Thus  $|A_0^0 x^0| > |\sum_i A_i^0 x^i|$ , which proves the announced result (for space like vectors  $x^2 < 0$ , the proof does not go through). Similarly if  $A_0^0 < -1$  the time component of a time-like vector reverses sign under  $A$ .

Thus we have found in  $L$  four disconnected sets of transformations:  $L^{+\uparrow}, L^{-\uparrow}, L^{+\downarrow}, L^{-\downarrow}$ . Correspondingly  $\mathcal{L}$  has four disconnected pieces.

*Decomposition of Lorentz transformations into plane reflections.*

*Def.* - The reflection  $\Sigma_{\mathbf{n}}$  through a plane orthogonal to  $\mathbf{n}$  is defined by

$$\mathbf{x}' = \mathbf{x} - 2 \frac{\mathbf{n} \cdot \mathbf{x}}{n^2} \mathbf{n}.$$

Note that  $\Sigma_{\mathbf{n}} = \Sigma_{-\mathbf{n}}$  and  $\Sigma_{\mathbf{n}} \mathbf{n} = -\mathbf{n}$ .

*Exercise 1.* - Show that  $\Lambda \Sigma_{\mathbf{n}'} \Lambda^{-1} = \Sigma_{\mathbf{n}}$  with  $\mathbf{n}' = \Lambda \mathbf{n}$  ( $\Sigma_{\mathbf{n}}$  is explicitly known,  $\Lambda^{-1} = (t \Lambda^T t)$ ).

*Exercise 2.* - If  $\mathbf{n}_i$  are linearly independent and  $A = \Sigma_{\mathbf{n}_1} \Sigma_{\mathbf{n}_2} \dots \Sigma_{\mathbf{n}_k}$

$$A \mathbf{p} = \mathbf{p} \Leftrightarrow \mathbf{n}_i \cdot \mathbf{p} = 0 \quad \text{for all } \mathbf{n}_i \quad (\Leftarrow \text{evident});$$

$A$  is of the form

$$A_{\nu}^{\mu} = g_{\nu}^{\mu} + \sum_{i,j} c_{ij} (n_i)_\nu (n_j)^\mu \quad \text{with } c_{ii} = -2(n_i)$$

and

$$(A \mathbf{p})^\mu = p^\mu + \sum_i \lambda_i p_i^\mu;$$

hence

$$\lambda_i = 0; \quad \lambda_i = \sum_j e_{ij} \mathbf{n}_j \cdot \mathbf{p};$$

for  $i = k$   $n_k \cdot \mathbf{p} = 0$  then  $i = k-1 \Rightarrow n_{k-1} \cdot \mathbf{p} = 0$ , then.....

**THEOREM.** - Any  $\Lambda \in L$  can be written as a product of at most 4 plane reflections. (This is a particular case of a stronger theorem:  $\Lambda$  « rotation » in  $k$ -dimensional space, i.e. a linear transformation leaving invariant the non-degenerate symmetric form

$$\sum_{i,j=1}^k g_{ij} x^i x^j \quad g_{ij} = g_{ji}$$

can be written as a product of at most  $k$  plane reflections).

The proof goes by induction on  $k$ .

We have three cases.

1)  $\exists \mathbf{x}$  such  $\Lambda \mathbf{x} = \mathbf{x}$  and  $\mathbf{x}^2 \neq 0$ . Then the  $k-1$  dimensional space  $\mathcal{E}_{k-1} + x$  is left invariant by  $\Lambda$ :  $\Lambda \mathcal{E}_{k-1} = \mathcal{E}_{k-1}$  and  $\Lambda$  is at most the product of  $k-1$  symmetries;

2) no invariant  $\mathbf{x}$  but  $\exists \mathbf{y}$  such that  $(\Lambda \mathbf{y} - \mathbf{y})^2 \neq 0$ . The symmetry  $\Sigma_{\mathbf{a}}$  (where  $\mathbf{a} = \Lambda \mathbf{y} - \mathbf{y}$ ) exchanges  $\Lambda \mathbf{y}$  and  $\mathbf{y}$ . Hence  $\Sigma_{\mathbf{a}} \Lambda$  leaves  $\mathbf{y}$  invariant, i.e. belongs to first case;

3) for all  $\mathbf{x}$ ,  $\mathbf{a} = \Lambda \mathbf{x} - \mathbf{x}$  is a light vector,

$$\mathbf{a}^2 = 0.$$

Part of this proof is more difficult in the general case, but in the case of real Lorentz group in 4 dimension it is very easy to prove that  $\Lambda$  is then the identity.

*The symmetries and the 4 pieces.*

$$(\Sigma_{\mathbf{n}})_{\nu}^{\mu} = q_{\nu}^{\mu} - 2 \frac{n^{\mu} n_{\nu}}{\mathbf{n}^2} \quad \Sigma_{\mathbf{n}}^2 = 1 \quad \text{Tr } \Sigma_{\mathbf{n}} = 2; \quad \det \Sigma_{\mathbf{n}} = -1$$

$$(\Sigma_{\mathbf{n}})_{\mathbf{0}}^{\mathbf{0}} = 1 - 2 \frac{n^{\mathbf{0}} n_{\mathbf{0}}}{\mathbf{n}^2} \quad \text{i.e.} \quad (\Sigma)_{\mathbf{0}}^{\mathbf{0}} = 1 - 2 \frac{(n^{\mathbf{0}})^2}{\mathbf{n}^2}, \quad \text{the sign of which is } -\mathbf{n}^2:$$

Hence  $\Sigma_{\mathbf{n}} \in L_{-}$ ; if  $\mathbf{n}$  time like  $\Sigma_{\mathbf{n}} \in L_{-}^{\downarrow}$ ,  
 $\mathbf{n}$  space like  $\Sigma_{\mathbf{n}} \in L_{-}^{\uparrow}$ .

Hence, elements of  $L^{\uparrow}$  = product of even  $(2, 4)$  number of  $\Sigma_{\mathbf{n}}$  with even  $[(0, 2, 4)$   
 number of time-like  $\mathbf{n}$

$L_+^\dagger =$  product of even number of  $\Sigma_{\mathbf{n}}$  with odd (1, 3) number of time-like  $\mathbf{n}$

$L_-^\dagger =$  product of odd (1, 3) number of  $\Sigma_{\mathbf{n}}$  with even number of time-like  $\mathbf{n}$

$L_+^\dagger =$  product of odd number of  $\Sigma_{\mathbf{n}}$  with odd number of time-like  $\mathbf{n}$

$L_+^\dagger$  is connected:

$$\forall \Lambda \in L_+^\dagger, \quad \Lambda = \Sigma_{\mathbf{n}_1} \Sigma_{\mathbf{n}_2} \Sigma_{\mathbf{n}_3} \Sigma_{\mathbf{n}_4}$$

Since the sign of  $\mathbf{n}$  is arbitrary, for time like vector  $\mathbf{n}$  choose the time component  $> 0$ . Now it is possible to vary continuously the time like vector to a fixed time like  $\mathbf{t}$ ; the space like, to a fixed  $\mathbf{s}$ ; since  $(\Sigma_{\mathbf{n}})^2 = 1$ , one has varied continuously  $\Lambda \rightarrow I$  (the identity), except in the case where the situation was for instance  $\Lambda = \Sigma_{\mathbf{s}} \Sigma_{\mathbf{t}} \Sigma_{\mathbf{s}} \Sigma_{\mathbf{t}} = \Sigma_{\mathbf{t}} \Sigma_{\mathbf{t}}$  where  $\mathbf{s}' = \Sigma_{\mathbf{t}} \mathbf{t}$  (from Exercise 2, p. 000), then when  $\mathbf{t}' \rightarrow \mathbf{t}$ ,  $\Lambda \rightarrow I$ .

Transitivity of  $L_+^\dagger$  on  $\mathcal{H}_{t_+}, \mathcal{H}_{t_-}, C_+, C_-, \mathcal{H}_s$ .

Notation defined on pages 11-12.

Remark. - If  $p'^2 = p^2$  and  $(p' + p)^2 \neq 0$ ,  $\Sigma_{p'+p}(-\mathbf{p}) = \mathbf{p}'$ .

Hence if

$$(p' - p)^2 \neq 0, \quad \Sigma_{p'-p} \mathbf{p} = \mathbf{p}'$$

We define

$$S_{p', p} = \Sigma_{p'+p} \Sigma_p$$

Now we can easily solve the problem:

Given  $p$  and  $p'$ , ( $p'^2 = p^2$ ) in the same  $\mathcal{H}_{t_+}$  (respectively  $\mathcal{H}_{t_-}, \dots$ ), find  $S \in L_+^\dagger$  such that  $p' = Sp$ .

Answer:

1) for  $\mathcal{H}_{t_+}$  (respectively  $\mathcal{H}_{t_-}$ );  $S_{p', p}$  (for  $\mathbf{p} + \mathbf{p}' \in \mathcal{H}_{t_+}$ ), hence  $S_{p', p} \in L_+^\dagger$ ;

2) for  $C_+$  (respectively  $C_-$ ):

If  $p', p$  are linearly independent  $(p' - p)^2 < 0$  let  $\mathbf{s}$  such that  $\mathbf{s}^2 < 0$ ,  $\mathbf{n} \cdot \mathbf{p} = \mathbf{n} \cdot \mathbf{p}' = 0$ ;  $\Sigma_{\mathbf{s}} \Sigma_p$  is a solution.

If  $p' = \alpha p$ , take  $\mathbf{t}$  time like ( $\Rightarrow \mathbf{t} \cdot \mathbf{p} \neq 0$ ) call  $p'' = \Sigma_{\mathbf{t}} p$  then  $\Sigma_{p''-p} \Sigma_p$  is a solution;

3) for  $\mathcal{H}_s$   $(p + p')^2 + (p - p')^2 = 4p^2 = 4p'^2 < 0$ , hence at least one of  $p + p'$  or  $p - p'$  is space like.

If  $p + p'$  space like  $S_{p', p}$  is solution  $p + p'$  time like  $\Sigma_{p'-p} \Sigma_p$  is solution ( $\mathbf{s}^2 < 0$ ,  $\mathbf{s} \cdot \mathbf{p} = \mathbf{s} \cdot \mathbf{p}' = 0$ ).

*Little group of vector.* - WIGNER called little group of  $p = L_p$ , the set of  $A$  such that  $Ap = p$ .

*p time like* from Exercise 2, page 12,  $L_p$  is generated by  $\Sigma_n$  with  $n \cdot p = 0$ , i.e.  $n$  space like. Hence  $L_p$  isomorphic to  $O_{(3)}$ , the orthogonal group into 3 dimensions. Its connected part is  $O_{(3)}^+$ , i.e. the group of rotations into 3 dimensions.

It can also be seen this way;  $L_p$  and  $A_0 L_p A_0^{-1}$  are isomorphic groups for a fixed  $A_0$ . Choose  $A_0$  such that  $A_0^{-1} p$  is on the time axis (if  $p$  is the four momentum,  $A_0^{-1} p$  brings the particle at rest).

*p space like* similar argumentation yields Lorentz group on space with one time axis, 2 space axis.

*p light like* the space orthogonal to  $p$  contains  $p: p^2 = 0$ . Let  $n_1, n_2$  transverse vectors orthogonal to  $p$ , i.e.

$$n_1 \cdot p = n_2 \cdot p = n_1 \cdot n_2 = 0 \quad \text{and} \quad n_i = (0, \mathbf{n}_i) \quad \text{hence} \quad n_1 \cdot p_2 = n_2 \cdot p = n_1 \cdot n_2 = 0$$

we take the  $n$  unitary

$$\mathbf{n}_1^2 = -\mathbf{n}_2^2 = \mathbf{n}_3^2 = -\mathbf{n}_4^2 = -1.$$

Call

$$\mathbf{n}' = \cos \frac{\theta}{2} \mathbf{n}_1 + \sin \frac{\theta}{2} \mathbf{n}_2; \quad \mathbf{n}' \cdot p = 0, \quad \mathbf{n}'^2 = -1.$$

The most general unit vector orthogonal to  $p$  is of the form ( $\alpha$  real arbitrary):

$$\mathbf{n}' + \alpha p, \quad \text{indeed} \quad (\mathbf{n}' + \alpha p) \cdot p = 0 \quad (\mathbf{n}' + \alpha p)^2 = -1.$$

The elements of the little group of  $p$  are therefore the product of at most 3 arbitrary symmetries of the type  $\Sigma_{\mathbf{n}' + \alpha p}$  (Exercise 2, page 12).

Connected little group. Its elements are the product of 2 symmetries

$$\Sigma_{\mathbf{n}' + \alpha p} \Sigma_{\mathbf{n}' + \alpha' p}$$

Let us call  $R(\theta) = \Sigma_n \Sigma_n$ ; it is a rotation around  $p$  of angle  $\theta$ ; so is

$$\Sigma_{n'} \Sigma_{n'} = R(\theta'' - \theta')$$

and call

$$T'(\alpha') = \Sigma_{\mathbf{n}' + \alpha' p} \Sigma_{n'}, \quad \text{example} \quad T(x_1) T_2(\alpha_2),$$

note  $\Sigma_n \Sigma_{n' - \alpha' p} = \Sigma_{n' - \alpha' p} \Sigma_n$  (see pages 12-13).

Any element of the connected little group of  $p$  can be written:

$$\Sigma_{n'+\alpha'p} \Sigma_{n'-\alpha'p} = \Sigma_{n'+\alpha'p} \Sigma_n^2 \Sigma_n^2 \Sigma_{n'-\alpha'p} = T(\alpha') R(\theta) T(\alpha')$$

We can generate the whole group from

$$R(\theta) T_1(\alpha_1) T_2(\alpha_2);$$

then  $\theta, \alpha_1, \alpha_2$  are the three parameters of the group.

From  $\Lambda \Sigma_n \Lambda^{-1} = \Sigma_{\Lambda n}$  that this group is just isomorphic to the 2 dimensional connected euclidean group, *i.e.* the group of translation  $t = \alpha_1 t_1 + \alpha_2 t_2$  and rotation around the origin of angle  $\theta$ . Indeed the group law is similar to that of the inhomogeneous Lorentz group and can be represented by the matrice

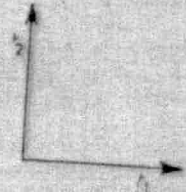


Fig. 4.

$$\begin{pmatrix} 1 & 0 & 0 \\ \alpha_1 & \cos \theta & -\text{sen } \theta \\ \alpha_2 & \text{sen } \theta & \cos \theta \end{pmatrix}$$

The isomorphism can be extended to the symmetries.  $\Sigma_{n1}$  corresponds to the symmetry defined by  $t_1$ , *i.e.* through  $t_2$  ( $\perp t_1$ ).

*Summary.* - Little group of  $p$ :

- $p$  time like: isomorphic to 3-dimensional rotation group,
- $p$  light like: isomorphic to 2-dimensional euclidean group,
- $p$  space like: isomorphic to 3-dimensional Lorentz group.

The covering group  $U_2$  of  $O_3^{(+)}$  (rotations in 3 dimensions). - We use the 3 Pauli matrices  $\tau = \{\tau_i\}$   $i = 1, 2, 3$  such that  $\tau_i^* = \tau_i$ ;

$$(30) \quad \tau_i \tau_j + \tau_j \tau_i = 2\delta_{ij}.$$

To each 3-vector  $x$ , we associate the matrix  $x = \sum_i x_i \tau_i = x \cdot \tau$ . Note that

$$(31) \quad x \cdot y = \frac{1}{2}(xy + yx); \quad x^2 = x^2$$

if  $x' = \Sigma_n x$  we have

$$(32) \quad x' = x - (nx + xn)n^{-2}n = -nxn^{-1}.$$

Let  $r_{21} = n_2 n_1$ ; it corresponds to the rotation

$$R_{21} = \Sigma_{n_2} \Sigma_{n_1} \quad \text{if} \quad \gamma = R_{21} \mathbf{x}$$

one has

$$(33) \quad \gamma = r_{21} \chi r_{21}^{-1} \quad \text{with } r_{21} = n_2 n_1.$$

From this it is easy to conclude that the matrices  $r$  multiply as do the rotations, *i.e.*

$$R \rightarrow r, \quad R' \rightarrow r', \quad R'' = RR' \rightarrow r'r' = r''.$$

This correspondence is however up to a sign, because  $\Sigma_n$  and  $\Sigma_{-n}$  are the same symmetry; hence both  $\pm r$  correspond to  $R$ .

If the rotation is defined by  $\mathbf{n}$ ,  $\omega$ , axis and angle of rotation  $r(\mathbf{n}, \omega)$  can easily be computed (use  $ab = a \cdot b + i(a \wedge b) \cdot \boldsymbol{\tau}$ ). We obtain taking  $\mathbf{n}^2 = 1$

$$r(\mathbf{n}, \omega) = \pm \left( \cos \frac{\omega}{2} - i n \sin \frac{\omega}{2} \right) = \pm \exp \left[ -i \frac{\omega}{2} n \right] = \pm u(\omega, \mathbf{n}),$$

*Remarks:*

a) The matrices  $u(\omega, \mathbf{n}) = \exp [-(i\omega/2)n]$  for all values of  $\mathbf{n}$  (with  $\mathbf{n}^2 = 1$ ) and  $\omega$  generates a group,  $U_2$  the unitary unimodular group.

Ideed

$$\omega_1, n_x, n_y, n_z \text{ real} \Rightarrow \left( \frac{\omega}{2} n \right)^* = \frac{\omega}{2} n \Rightarrow u \text{ unitary}$$

$$\text{tr } n = 0 \Rightarrow \det u = 1.$$

b) Conversely a unitary 2 by 2 matrix  $u$  can be written  $u = \exp [-ih]$  where  $h$  is a 2 by 2 hermitian matrix and any  $h$  can be written  $(\omega/2)n$ .

c) What we have found therefore is not a true representation of the rotation group  $O_3^{(+)}$  but a representation *up to a sign only*.

We also prove  $U_2 \xrightarrow{f} O_3^{(+)}$ , where the homomorphism  $f$  is a two to one correspondence. Kernel of  $f$  is  $u = 1$  and  $u = -1$  (which form the two element group  $Z_2$ ).  $\pm u(\omega, \mathbf{n}) \rightarrow r(\omega, \mathbf{n})$ .

d) Note that  $u(2\pi, \mathbf{n}) = -1$  whatever  $\mathbf{n}$ .

*Definition of Poincaré group,  $\pi_1$ .* - For a topological group consider continuous mapping  $s_1$  of the circle  $S_1$  (= sphere in 1 dimension; we can generalize to  $S_n$ ) into the group manifold and such that this mapping contains the

identity. (By translation on the group any other fixed point can be chosen). If a given  $s_1$  called  $s_1'$  can be, by continuous transformation, transformed into  $s_1''$  (another  $s_1$ ), then  $s_1'$  and  $s_1''$  are said « homotopic ». It is easy to see that « homotopy » is an equivalence relation among the  $s_1$ . We can define the « product » of two  $s_1$ , when  $S_1$  is oriented. This  $\Rightarrow$  a composition law for the equivalence class, which gives a group structure. (the identity class is that of the  $s_1$  which, by continuous deformation can be reduced to a point). This group is called  $\pi_1$  or Poincaré group.

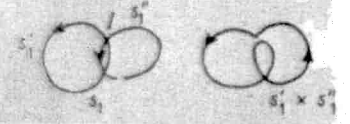


Fig. 5.

*Simply connected group.* - It is a group whose Poincaré group has only one element. All closed paths in the group are homotopic. Example,  $U_2$  is simply connected.

The most general matrix of  $U_2$  is of the form

$$\begin{vmatrix} \alpha & \beta \\ \bar{\beta} & \alpha \end{vmatrix}$$

with  $\alpha\bar{\alpha} + \beta\bar{\beta} = 1$ . If  $\alpha = \alpha_1 + i\alpha_2$ ,  $\beta = \beta_1 + i\beta_2$ , the condition is  $\alpha_1^2 + \alpha_2^2 + \beta_1^2 + \beta_2^2 = 1$ . This is the equation of  $S_3$ , the 3 dimensional sphere. Consider a closed path in it, passing through the point 1, 0, 0, 0 (unit of the group). By continuous deformation this path can be made « plane » (i.e. contained in a 3 dimensional plane) and this plane can be moved continuously to the tangent plane in 1, 0, 0, 0.

*Covering group  $C$  of  $G$ .* - It can be shown (see C. J. PONTRJAGIN: *Topological Groups*, § 47, for the proof and the precise sufficient conditions) that for any Lie group  $G$ , there exists a *unique* simply connected group  $C$ , locally isomorphic to  $G$ , homomorphic to  $G$ . Then, the kernel  $\pi_1$  of the homomorphism is isomorphic to the Poincaré group of  $G$ . This unique  $C$  is called the covering group of  $G$ . We have therefore proved that  $U_2$  is the covering group of  $O_3^+$ . We also know the two homotopy class of paths of  $O_3^+$ . The identity class is that of closed paths which are image (by the homomorphism  $U \rightarrow O_3^+$ ) of closed path of  $U$ . They can be shrunk to a point since  $U$  is simply connected. The closed paths in  $O_3^+$  which are image of continuous path from 1 to  $-1$  in  $U$  cannot be shrunk to a point. A way to « see » the topology of  $O_3^+$  is to plot each rotation  $n, \omega$  at the tip of the vector  $\omega n$  with  $0 < \omega \leq \pi$  and identify the points  $\pm \omega n$ ; closed paths which contain an odd number of such points  $\pm \omega n$  cannot be homotopic to zero.

*The covering group  $C_2$  of  $L_2^+$ .* - What we have done for  $O_3^+$  with the Pauli matrices can be done now for the Lorentz group  $L$  and the Dirac matrices

(34)  $[i\gamma^\mu, i\gamma^\nu]_+ = 2g^{\mu\nu}$  when  $[A, B]_+ = AB + BA$ .

We write  $i\gamma^\mu$  for the matrices, because it is possible to choose the  $i\gamma^\mu$  real. Indeed the  $i\gamma^\mu$  generate an algebra of 16 linearly independent matrices

$$\gamma^{\lambda A} = 1, \gamma^\mu, i\sigma^{\mu\nu} = \frac{1}{2}[\gamma^\mu, \gamma^\nu], \gamma^5\gamma^\mu, \gamma^5 = \gamma^0\gamma^1\gamma^2\gamma^3.$$

The 32 matrices  $\pm \gamma^{\lambda A}$  form a group of elements  $\gamma^{\lambda A}$ . We can compute (see pages 555, 666)

$$(35) \quad \frac{1}{32} \sum_A \text{Tr} (\gamma^{\lambda A})^2 = \frac{1}{16} \sum_A \text{Tr} (\gamma^{\lambda A})^2 = 1.$$

We define the correspondence  $\mathbf{x} \rightarrow X$ .

Equations similar to (31), (32), (33) hold.

To summarize,  $A \in L^\dagger$  can be decomposed into (see page 14)

$$A = \sum_{n_1} \sum_{n_0} \sum_{n_2} \sum_{n_1} \quad \text{with } |n_i^2| = 1.$$

The correspondence  $A \rightarrow \pm n_4 n_3 n_2 n_1 = S(A)$  is a representation up to a sign of  $L^\dagger$ .

This representation is reducible

$$i\gamma^5 S(A) = S(A) i\gamma^5.$$

Since  $(i\gamma^5)^2 = 1$  and  $\text{tr} \gamma^5 = 0$ ,  $\gamma^5$  can be written

$$\tau_3 \otimes 1 = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix}$$

and one finds easily that the real four dimensional representation  $S(A)$  breaks into the direct sum of two charge conjugated two dimensional representations: e.g. take

$$\gamma^0 = (\tau_1 \otimes \tau_1); \quad \gamma^1 = (i\tau_2 \otimes 1).$$

Another method to prove it directly is:

We form the matrices  $X$  for a given  $\mathbf{x}$  according to

$$36) \quad \left\{ \begin{array}{l} X = x^0 \cdot 1 - \sum_i x^i \tau_i \\ \mathbf{x}: X = \begin{pmatrix} x^0 + x^3 & x^1 - ix^2 \\ x^1 + ix^2 & x^0 - x^3 \end{pmatrix} \end{array} \right.$$



and notice that  $\det X = x^2$ .

Corresponding to  $x' = Ax$  we write

$$X'^{\mu\nu} = A^{\mu\rho}{}_{\sigma\alpha} X^{\sigma\alpha}.$$

For a light-like vector  $x$  ( $x^2 = 0$ ) this has the form

$$\alpha^\mu \beta^\nu = A^{\mu\rho}{}_{\sigma\alpha} \xi^\sigma \eta^\alpha.$$

In this case one finds that it is possible to write

$$(37) \quad X' = AXB^T \quad \text{or} \quad X' = \Delta X^T B^T,$$

where the requirement  $\det X' = \det X$  imposes the condition  $\det A \cdot \det B = 1$  which leaves a great choice of possible  $A, B$ . If we suppose that  $\det A = \det B = 1$  we still have an ambiguity in sign: we can choose either  $A$  and  $B$  or  $-A$  and  $-B$ .

*The real homogeneous connected Lorentz group.* - For this group  $x$  is real and  $X$  hermitian

$$(39) \quad X^* = X, \quad X'^* = X'.$$

So that

$$(B^T)^* X A^* = \Delta X B^T.$$

or equivalently

$$X A^* (B^T)^{-1} = (B^T)^{* -1} \Delta X$$

or

$$X A^* (B^T)^{-1} = [A^* (B^T)^{-1}]^* X.$$

Writing

$$F = A^* (B^T)^{-1}$$

we have

$$XF = F^* X;$$

this holds for all hermitian matrices, in particular for  $X = 1$  so that

$$F = F^*.$$

By Schur's Lemma  $\exists$  a scalar  $\lambda$  such that

$$F = \lambda I$$

so that

$$A^* = \lambda B^T;$$

but  $\det A = \det B$  so that

$$A^* = \pm B^T.$$

For the group  $L_+^\uparrow$ :

$$(40) \quad X' = +AXA^*;$$

for the set (not a group!)  $L_-^\uparrow$ :  $X' = -AXA^*$ .

Conversely, take an  $A$  such that  $\det A = 1$ : the correspondence  $X \rightarrow X' = AXA$  is a linear correspondence  $\mathbf{x} \rightarrow \mathbf{x}'$  preserving  $\mathbf{x}^2$ .

Thus we have a homomorphism between the Unimodular group  $C_2$ , i.e. the group of all  $2 \times 2$  matrices of determinant 1, and  $L_+^\uparrow$ :

$$A \in L_+^\uparrow \rightarrow \pm A n G_2.$$

*Examples.* - Rotation:

$$(41) \quad (n, \omega), \quad A \text{ unitary } U = (U^*)^{-1} = \pm \left( \cos \frac{\omega}{2} - i \mathbf{n} \cdot \boldsymbol{\tau} \sin \frac{\omega}{2} \right).$$

« Pure » Lorentz transformation:

$$(41') \quad (\mathbf{l}, \beta), \quad A \text{ hermitian positive definite } = H = H^* = \pm \left( \text{ch} \frac{\beta}{2} + \mathbf{l} \cdot \boldsymbol{\tau} \text{sh} \frac{\beta}{2} \right)$$

(a change in « velocity »  $\beta$  (th  $\beta = v/c$ ) in the  $\mathbf{l}$  direction).

Now, any matrix can be written as the product of a unitary matrix  $U$  and a hermitian positive definite matrix  $H$ :

$$(42) \quad A = UH;$$

$AA^*$  is a positive definite hermitian matrix:  $AA^* = H^2 \rightarrow \exists$  a unique positive definite square root of  $H^2$ :  $H \cdot H^{-1}A \cdot A^*H^{-1} = (H^{-1}A)(H^{-1}A)^* = 1$ ; since  $H^{-1}A$  exists  $H^{-1}A$  is unitary:  $A = HU$ .

Thus every Lorentz transformation has a unique decomposition into the product of a rotation and a pure Lorentz transformation.

We have also explicitly displayed the 6 parameters of the  $L_+^\uparrow$ . Note that if we consider « imaginary rotations »  $n$ ,  $i\omega$  one just obtains the « pure » Lorentz transformation  $\mathbf{l} = n$ ,  $\beta = \omega$  (see (41) and (41')).

This shows that  $L_+^\uparrow$  is isomorphic to the complex rotation group  $CO_3^{(c)}$  in the same way  $C_2$  is the « complex group » of  $U_2$ . We leave to the reader to prove that  $C_2$  is the covering group of  $L_+^\uparrow$  with  $C_2/Z_2 = L_+^\uparrow$ .

*Complex Lorentz group CL.* - If we do not add condition (39) to the conditions (37) and (38) we obtain a representation up to a sign of the complex Lorentz group  $CL$  (= complex connected orthogonal group  $CO_4^+$ ), i.e. the group, for which  $x^2$  is invariant for all  $x$  with complex co-ordinates. Any  $\in CL$  is represented, up to a sign, by a couple of unimodular  $2 \times 2$  matrices  $A$  and  $B$ .

Hence the direct product  $C_2 \times C_2$  is a representation up to a sign of  $CL$ , i.e.

$$(43) \quad CL = C_2 \times C_2 / Z_2.$$

*Lie algebra of the inhomogeneous Lorentz group.* - As we saw, a general element of the group may be written

$$A = \begin{pmatrix} 1 & 0 \\ a & A \end{pmatrix} \equiv A(\dots \alpha^i \dots),$$

where  $\alpha^i$  are the parameters labelling the elements and for the identity

$$I = A(0, 0, \dots).$$

We construct the infinitesimal operators in the neighbourhood of the identity defined by (see Prof. RACAH's lecture):

$$(44) \quad D_i = \left( \frac{\partial A}{\partial \alpha^i} \right)_{\alpha^i=0}.$$

For a one parameter abelian group (if it exists) we have

$$A(\alpha_1^i + \alpha_2^i) = A(\alpha_1^i)A(\alpha_2^i),$$

where  $\alpha_1^i, \alpha_2^i$  are two values of the same parameter

We solve this functional equation by differentiating with respect to  $\alpha_1^i$  holding  $\alpha_2^i$  fixed, and then putting  $\alpha_1^i = 0$ :

$$A_1^i(\alpha_2^i) = D_i A(\alpha_2^i).$$

Thus we have

$$A(\alpha^i) = \exp[\alpha^i D_i].$$

We remark that since the exponential of a matrix is well defined there is no difficulty when the operators are matrices; it should be remembered that if

$$[D_1, D_2] \neq 0, \quad \exp[D_1 + D_2] \neq \exp[D_1] \cdot \exp[D_2].$$

*Translation group.* - For an infinitesimal translation  $A(a, 1) \simeq 1 + \mathcal{D}_\mu a^\mu$ , where  $a^\mu$  are the parameters and  $\mathcal{D}_\mu$  are the four corresponding infinitesimal operator. For a finite translation we obtain

$$(5) \quad U(a, 1) = \exp[\mathcal{D}_\mu a^\mu] = \exp[iP_\mu a^\mu],$$

where we have introduced

$$P_\mu = -\mathcal{D}_\mu.$$

Physicists introduce  $P$ , because when  $U$  is unitary,  $P^\mu$  are hermitian and are observables. Indeed they correspond to energy and momentum. The transformation properties of  $P^\mu$  and  $L^\mu_\nu$  can be obtained by the use of (4):

$$(6) \quad U(0, A)U(a, 1)U(0, A)^{-1} = U(Aa, 1)$$

and (16); one obtains

$$(7) \quad U(0, A)P^\mu U(0, A)^{-1} = A^\mu_\nu P^\nu.$$

Furthermore the  $\mathcal{D}^\mu$  commute hence

$$(8) \quad [P^\mu, P^\nu] = 0.$$

**Homogeneous group**

$$A^x G A = G.$$

The treatment is very similar to that of the orthogonal rotation group. For  $A \in O_n$ ,  $A^t A = 1$ .

Differentiation with respect to a parameter yields (by putting the parameter equal to zero)

$$A^x|_{x=0} 1 + 1 A^x|_{x=0} = 0,$$

$$D^x + D = 0.$$

For the homogeneous Lorentz group we have from (4)

$$M^x G + G M^x = 0$$

putting

$$D = G M^x.$$

We have  $D' + D = 0$ , i.e.  $D$  is skewsymmetric. It is  $4 \times 4$  so there are six parameters.

We define the matrices  $e_{\alpha\beta}$  as before

$$(51) \quad (e_{\alpha\beta})_{\mu\nu} = \delta_{\alpha\mu} \delta_{\beta\nu}$$

that is

$$(52) \quad e_{\alpha\beta} e_{\beta\alpha} = e_{\alpha\alpha} e_{\beta\beta}.$$

These  $e_{\alpha\beta}$  provide us with a convenient representation of the  $D_{\mu\nu}$  (infinitesimal operator of the rotation in the 2-plane  $\mu - \nu$ )

$$D_{\mu\nu} = e_{\mu\nu} - e_{\nu\mu}.$$

We have

$$\begin{aligned} D_{\mu\nu} D_{\rho\sigma} &= (e_{\mu\nu} - e_{\nu\mu})(e_{\rho\sigma} - e_{\sigma\rho}) \\ &= e_{\mu\nu} e_{\rho\sigma} + e_{\nu\mu} e_{\sigma\rho} - e_{\nu\mu} e_{\rho\sigma} - e_{\mu\nu} e_{\sigma\rho} \\ &= e_{\mu\sigma} \delta_{\nu\rho} + e_{\nu\rho} \delta_{\mu\sigma} - e_{\nu\sigma} \delta_{\mu\rho} - e_{\mu\rho} \delta_{\nu\sigma} \end{aligned}$$

hence

$$(53) \quad [D_{\mu\nu}, D_{\rho\sigma}] = D_{\mu\sigma} \delta_{\nu\rho} + D_{\nu\rho} \delta_{\mu\sigma} - D_{\nu\sigma} \delta_{\mu\rho} - D_{\mu\rho} \delta_{\nu\sigma}.$$

Introducing

$$(54) \quad M = iM = i\mathcal{G}D,$$

$$(55) \quad [M_{\mu\nu}, M_{\rho\sigma}] = i[g_{\nu\sigma} M_{\mu\rho} + g_{\mu\rho} M_{\nu\sigma} - g_{\nu\rho} M_{\mu\sigma} - g_{\mu\sigma} M_{\nu\rho}].$$

Since the homogeneous Lorentz group is semi-simple we may find the Casimir operators in a straight forward way (see Prof. RACAH lecture).

So far we have only in (55) the Lie algebra of  $L_{\dagger}$ . That is, given any two elements, we know their commutator, not their products.

*Enveloping algebra of a Lie algebra.* - Example  $L$  and  $\mathcal{L}$ .

This consists of all possible formal polynomials formed from the elements of the Lie algebra.

*Centre of the enveloping algebra.* - The centre  $\mathcal{C}$  of the enveloping algebra  $E$  is the set of all elements  $e \in E$  which commute with every other element:

$$\mathcal{C} = \{e \in E \mid \forall f \in E \cdot fe = ef\}.$$

Centre of the enveloping algebra of the inhomogeneous group. — It is convenient to define the 3 dimensional « pseudovector »

$$(56) \quad \mathbf{J} = (J^1, J^2, J^3) = (M^{23}, M^{31}, M^{12})$$

and the 3-vector

$$(56') \quad \mathbf{N} = (N^1, N^2, N^3) = (M^{01}, M^{02}, M^{03}).$$

We have from (55)

$$(57) \quad [J^i, J^j] = i\epsilon^{ijk}J^k,$$

which physicists write symbolically

$$(57') \quad \mathbf{J} \wedge \mathbf{J} = i\mathbf{J}.$$

We also obtain

$$(58) \quad \mathbf{N} \wedge \mathbf{N} = -i\mathbf{J},$$

$$(58') \quad [J_i, N_j] = i\epsilon_{ijk}N_k = [N_i, J_j].$$

As is well known

$$[\mathbf{J}^2, \mathbf{J}] = \mathbf{0},$$

but

$$[\mathbf{J}^2, \mathbf{N}] \neq \mathbf{0}, \quad [\mathbf{N}^2, \mathbf{N}] \neq \mathbf{0}.$$

For the homogeneous group the invariants (*i.e.* elements of the center) are

$$(59) \quad \mathbf{J}^2 = \mathbf{N}^2 = \frac{1}{2}M^{\mu\nu}M_{\mu\nu}; \quad \mathbf{J} \cdot \mathbf{N} = \frac{1}{2}\epsilon^{\lambda\mu\nu\sigma}M_{\lambda\mu}M_{\nu\sigma} = \det M_{\mu\nu}$$

They do not, however, commute with the  $P$ 's and so do not belong to the Centre for the inhomogeneous group.

For the inhomogeneous group we have to include the elements  $P_\mu$  of the translation group. We find

$$(60) \quad [P_\lambda, M_{\mu\nu}] = i(g_{\lambda\mu}P_\nu - g_{\lambda\nu}P_\mu)$$

so that using  $[A[B, C] + A[B, C]] = [A, C]B$  we find that:  $P^2 = P^\mu P_\mu$  commutes with  $M_{\mu\nu}$ .

It also commutes with the  $P$ 's so that it is one element of the centre. The other invariant was found by Pauli: let

$$W_1 = \frac{1}{2}\epsilon^{\lambda\mu\nu\sigma}P_\lambda M_{\mu\nu}$$

then

$$P_\lambda W^\lambda = 0$$

and

$$[P_\mu, W_\lambda] = 0.$$

We compute

$$[W_\lambda, M_{\mu\nu}] = i(g_{\lambda\mu} W_\nu - g_{\lambda\nu} W_\mu),$$

$$[W_\lambda, W_\mu] = i\varepsilon_{\lambda\mu\nu\rho} P^\nu W^\rho,$$

(note that  $\varepsilon^{\lambda\mu\nu\rho} = -\varepsilon_{\lambda\mu\nu\rho}$  since  $\det g = -1$ ;  $\varepsilon^{0123} = 1$ ).

We see that

$$W^2 = W_\mu W^\mu$$

is also an element of the centre of the envelopping algebra.

*Summary.* - Invariants:

$$\text{for } \mathcal{L} \quad P^2, \quad W^2,$$

$$\text{for } L: \quad J^2 - N^2, \quad \mathbf{J} \cdot \mathbf{N}.$$